

DISCLAIMER. This document is © Gerard Sayson 2025, all rights reserved. These solutions were prepared independently by the author. While care has been taken to ensure accuracy, errors may still be present, and the solutions should be used as a learning aid rather than an authoritative reference. The author assumes no responsibility or liability for any inaccuracies, misinterpretations, or consequences arising from the use of this document. For corrections or feedback, please email gerard@gsn.bz. This document was last updated on November 17, 2025.

1 Suppose $a, b > 0$.

Let $q_1 = 2a$ and $q_{n+1} = 2a + b^2/q_n$. Since $(q_n)_{n \in \mathbb{N}}$ converges, let $q_n q_{n+1} = 2aq_n + b^2$. Note that $L^2 - 2aL - b^2 = 0$ so $L = a \pm \sqrt{a^2 + b^2}$. Notice that all terms in the sequence are positive so $L = a + \sqrt{a^2 + b^2}$, otherwise $L = a - \sqrt{a^2 + b^2} < 0$ which is impossible, as $a < \sqrt{a^2 + b^2}$.

- 2 (a) Let $z_1 = 5 + i$ and $z_2 = 239 + i$. Then $|z_1| = \sqrt{26}$ and $|z_2| = \sqrt{57122}$. Also, $\arg(z_1) = \tan^{-1}(\frac{1}{5})$ and $\arg(z_2) = \tan^{-1}(\frac{1}{239})$.
- (b) By considering the properties of $re^{i\theta}$, see that $|z_4| = |z_1|^4/|z_2| = \frac{676}{\sqrt{57122}} = \sqrt{\frac{456976}{57122}} = 2\sqrt{2}$. Also, $\arg(z_4) = 4\arg(z_1) - \arg(z_2) = 4\tan^{-1}(\frac{1}{5}) - \tan^{-1}(\frac{1}{239})$.
- (c) We are to show $\arg(z_4) + \arg(z_3) = 4\arg(z_1)$, i.e. we must literally find $\arg(z_4)$. By GC,

$$\frac{z_1^4}{z_2} = \frac{(5+i)^4}{239+i} = 2+2i.$$

Hence $\arg(z_4) = \tan^{-1}(1) = \frac{1}{4}\pi$, and the conclusion follows.

3 (a) $x^2 + (y+a)^2 = r^2$.

(b) Write $y = \sqrt{r^2 - x^2} - a$. Set $y = 0$ so $x = \pm\sqrt{r^2 - a^2}$. Also note that

$$\frac{dy}{dx} = -\frac{x}{\sqrt{r^2 - x^2}}.$$

Hence

$$\begin{aligned} & 2\pi \int_{-\sqrt{r^2-a^2}}^{\sqrt{r^2-a^2}} (\sqrt{r^2-x^2} - a) \sqrt{1 + \left(\frac{x}{\sqrt{r^2-x^2}}\right)^2} dx \\ &= 2\pi \int_{-\sqrt{r^2-a^2}}^{\sqrt{r^2-a^2}} (\sqrt{r^2-x^2} - a) \sqrt{\frac{r^2}{r^2-x^2}} dx \\ &= 2\pi r \int_{-\sqrt{r^2-a^2}}^{\sqrt{r^2-a^2}} \left(1 - \frac{a}{\sqrt{r^2-x^2}}\right) dx \\ &= 2\pi r \left[x - a \sin^{-1}\left(\frac{x}{r}\right) \right]_{-\sqrt{r^2-a^2}}^{\sqrt{r^2-a^2}} \\ &= 4\pi r \left(\sqrt{r^2-a^2} - a \sin^{-1}\left(\frac{\sqrt{r^2-a^2}}{r}\right) \right). \end{aligned}$$

Here, $k = 4\pi$.

4 (a) $L \approx \pi\sqrt{2} + \frac{3\sqrt{2}}{2}\pi \approx 11.10721 \approx 11.1072$ (4dp).

(b) (i) $\frac{dy}{dx} = \sin(x) + x \cos(x)$ so $L = \int_0^{2\pi} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx = \int_0^{2\pi} \sqrt{1 + (\sin(x) + x \cos(x))^2} dx$.

(ii) The size of each interval is $\frac{1}{4} \times 2\pi = \frac{\pi}{2}$. Hence, letting $f(x) = \sqrt{1 + (\sin(x) + x \cos(x))^2}$,

$$L \approx \frac{\pi}{4} \left(f(0) + 2f\left(\frac{\pi}{2}\right) + 2f(\pi) + 2f\left(\frac{3\pi}{2}\right) + f(2\pi) \right) \approx 15.40396 \approx 15.4040 \text{ (4dp)}.$$

(iii) $L \approx 15.37457 \approx 15.3746$ (4dp) by GC.

(c) The student's approximation is inaccurate because it is far from the true (GC) value, while the trapezium rule approximation is accurate because it is close to the true value.

5 (a) $z = f(x, y) = x \tan^2(y)$, so $\frac{\partial z}{\partial x} = \tan^2(y)$ and $\frac{\partial z}{\partial y} = 2x \tan(y) \sec^2(y)$. Hence

$$\begin{aligned} z &= f\left(2, \frac{\pi}{4}\right) + (x-2)f_x\left(2, \frac{\pi}{4}\right) + \left(y - \frac{\pi}{4}\right)f_y\left(2, \frac{\pi}{4}\right) = 2 + (x-2)(1) + \left(y - \frac{\pi}{4}\right)(8) \\ \implies z &= x + 8y - 2\pi \implies x + 8y - z = 2\pi. \end{aligned}$$

Then $a = 1$, $b = 8$ and $c = -1$.

(b) A vector normal to the plane is $\begin{pmatrix} 1 \\ 8 \\ -1 \end{pmatrix}$.

(c) Calculate $\mathbf{u} = \mathbf{i} + \mathbf{j}$ and $\mathbf{v} = \mathbf{i} + 8\mathbf{k}$. Then $\mathbf{u} \times \mathbf{v} = \begin{pmatrix} 1 \\ 8 \\ -1 \end{pmatrix}$ which is normal to the plane.

(d) Both $\mathbf{u}$ and $\mathbf{v}$ are direction vectors on P . $\mathbf{u}$ is the direction vector giving the directional derivative along the x -axis at the point P , while $\mathbf{v}$ is that along the y -axis.

6 (a) The *annual* interest rate is $(1.008^{12} - 1) \times 100\% \approx 1.10\%$ (3sf). F is the minimum amount the business repays per month, and G is the additional amount that the business pays per month as the number of months passed increases and more interest is charged monthly.

(b) Let

$$\overbrace{A \times 1.008^{n+1} + B(n+1) + C}^{M_{n+1}} = \overbrace{1.008(A \times 1.008^n + Bn + C)}^{1.008M_n} - F - Gn.$$

Then $Bn + B + C = 1.008Bn + 1.008C - F - Gn \implies 0.008Bn - B + 0.008C = F + Gn$. Hence $B = 125G$ and $-B + 0.008C = -125G + 0.008C = F \implies C = 125(F + 125G)$. It now remains to determine A . Since $M_0 = 10^6 = A + C$, $A = 10^6 - C = 10^6 - 125(F + 125G)$.

(c) Set $M_{60} = 0$. Then

$$(10^6 - 125(F + 125G)) \times 1.008^{60} + 60 \times 125G + 125(F + 125G) = 0$$

and we solve for G in terms of F . Indeed,

$$-15625 \times 1.008^{60} \times G + (10^6 - 125F) \times 1.008^{60} + 23125G + 125F = 0$$

$$G = \frac{(10^6 - 125F) \times 1.008^{60} + 125F}{15625 \times 1.008^{60} - 23125}.$$

Since G varies linearly with F and is decreasing, $\max_{F \geq 2500} G \approx 684$ (3sf) occurs at $\min_{F \geq 2500} F = 2500$.

7 (a) T admits two eigenvalues, one with multiplicity 2. By GC,

$$p_T(\lambda) = \begin{vmatrix} 1-\lambda & 2 & 1 \\ 3 & 2-\lambda & -1 \\ 3 & -2 & 3-\lambda \end{vmatrix} = (\lambda+2)(\lambda-4)^2 = 0$$

implies $\lambda = -2$ or $\lambda = 4$.

If $\lambda = 4$, then

$$[T - \lambda \cdot \text{id}]_{\beta} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \mathbf{0} \implies \begin{pmatrix} -3 & 2 & 1 \\ 3 & -2 & -1 \\ 3 & -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \mathbf{0} \implies \begin{pmatrix} -3 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \mathbf{0}.$$

Hence $z = 3x - 2y$, and the equation of Π is

$$\Pi : \mathbf{r} = a \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix} \quad \forall a, b \in \mathbb{R}.$$

Else if $\lambda = -2$, then

$$\text{rref} \begin{pmatrix} 3 & 2 & 1 \\ 3 & 4 & -1 \\ 3 & -2 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \implies l : \mathbf{r} = a \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \quad \forall a \in \mathbb{R}.$$

- (b) (i) For no unique solutions, $\det(T - t \cdot \text{id}) = 0$. Hence the values of t are the eigenvalues of T , i.e. $t = -2$ and $t = 4$.
- (ii) If $t = -2$ then $(a, b, c) \in \mathbb{R}^3$ must be on l . Hence $-a = b = c$ for a solution to exist.
If $t = 4$ then (a, b, c) must lie on Π . Hence $c = 3a - 2b$.

8 (a) $u = x \frac{dy}{dx} + y \implies \frac{du}{dx} = x \frac{d^2y}{dx^2} + 2 \frac{dy}{dx} \implies \frac{d^2u}{dx^2} = x \frac{d^3y}{dx^3} + 3 \frac{d^2y}{dx^2}$. Hence $\frac{d^2u}{dx^2} + u = 2$.

The characteristic equation is $\lambda^2 + 1 = 0$ so $\lambda = \pm i$. Hence a solution to the *complementary* equation in u is $u = C_1 \sin(x) + C_2 \cos(x)$ for all $C_1, C_2 \in \mathbb{R}$. Thus a solution to the nonhomogenous DE in u is $u = C_1 \sin(x) + C_2 \cos(x) + 2$.

Let $C_1 \sin(x) + C_2 \cos(x) + 2 = x \frac{dy}{dx} + y$. Then let $v = xy$ so $\frac{dv}{dx} = x \frac{dy}{dx} + y = C_1 \sin(x) + C_2 \cos(x) + 2$.
Hence

$$v = -C_1 \cos(x) + C_2 \sin(x) + 2x + C_3 \implies y = -\frac{C_1 \cos(x)}{x} + \frac{C_2 \sin(x)}{x} + 2 + \frac{C_3}{x}.$$

$$\frac{dy}{dx} = C_1 \times \frac{x \sin(x) + \cos(x)}{x^2} + C_2 \times \frac{x \cos(x) - \sin(x)}{x^2} - \frac{C_3}{x^2}.$$

When $x = \frac{\pi}{2}$, $y = 2$ and $\frac{dy}{dx} = -\frac{2}{\pi}$:

$$\frac{2C_2}{\pi} + 2 + \frac{2C_3}{\pi} = 2 \implies C_2 = -C_3,$$

$$\frac{2C_1}{\pi} - \frac{4C_2 + 4C_3}{\pi^2} = -\frac{2}{\pi} \implies C_1 = -1.$$

When $x = \pi$, $y = 2 + \frac{1}{\pi}$ and $\frac{dy}{dx} = \frac{2}{\pi} - \frac{1}{\pi^2}$.

$$-\frac{1}{\pi} + 2 + \frac{C_3}{\pi} = 2 + \frac{1}{\pi} \implies C_3 = 2 \implies C_2 = -2.$$

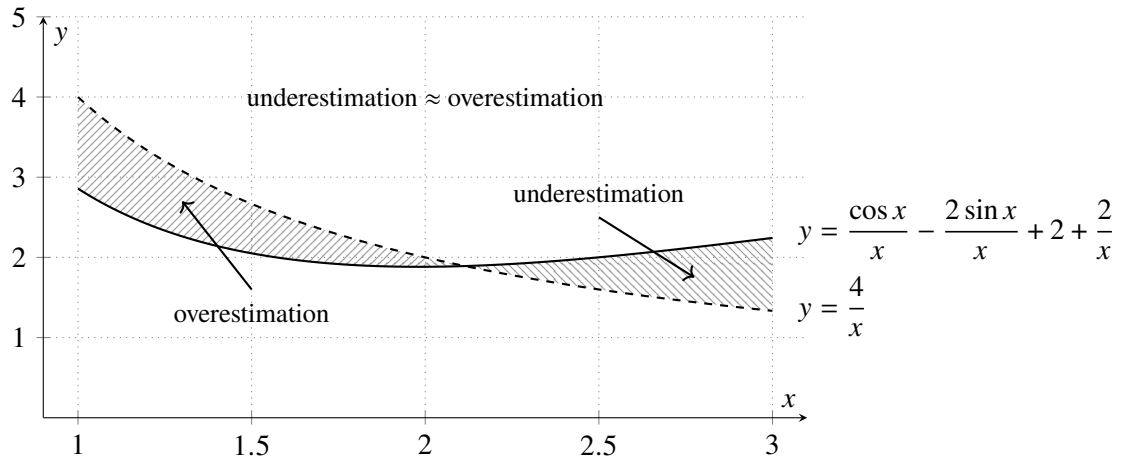
It follows that

$$y = \frac{\cos(x)}{x} - \frac{2 \sin(x)}{x} + 2 + \frac{2}{x}.$$

- (b) By GC, $\int_1^3 \left(\frac{\cos(x)}{x} - \frac{2 \sin(x)}{x} + 2 + \frac{2}{x} \right) dx \approx 4.17431$ and $\int_1^3 \frac{4}{x} dx \approx 4.39445$, both values to 5dp.

The relative error $\varepsilon = \left| \frac{4.17431 - 4.39445}{4.17431} \right| \times 100\% \approx 5.27\%$ to 3sf, which is a small error.

Considering the graphs:



the area of the overestimation is approximately the area of the underestimation, so $\int_1^3 y \, dx = \int_1^3 \frac{4}{x} \, dx -$
 overestimation + underestimation $\approx \int_1^3 \frac{4}{x} \, dx$ and so $\int_1^3 \frac{4}{x} \, dx$ is suitable to approximate $\int_1^3 y \, dx$.

- 9 (a) Write $Q = \Sigma(y - ax^2 - bx)^2$. Then $(y - ax^2 - bx)^2 = y^2 + a^2x^4 + b^2x^2 - 2ax^2y - 2bxy + 2abx^3$. Hence $Q = \Sigma(y^2 + a^2x^4 + b^2x^2 - 2ax^2y - 2bxy + 2abx^3) = \Sigma(y^2) + a^2\Sigma(x^4) + b^2\Sigma(x^2) - 2a\Sigma(x^2y) - 2b\Sigma(xy) + 2ab\Sigma(x^3)$.
- (b) $\frac{\partial Q}{\partial a} = 2a\Sigma(x^4) - 2\Sigma(x^2y) + 2b\Sigma(x^3)$ and $\frac{\partial Q}{\partial b} = 2b\Sigma(x^2) - 2\Sigma(xy) + 2a\Sigma(x^3)$.
- (c) (i) Since Q is minimal, $\nabla Q = \mathbf{0}$. Hence

$$\begin{aligned} a\Sigma(x^4) + b\Sigma(x^3) &= \Sigma(x^2y) \\ a\Sigma(x^3) + b\Sigma(x^2) &= \Sigma(xy) \end{aligned}$$

and this is a linear system such that $\overbrace{\begin{pmatrix} \Sigma(x^4) & \Sigma(x^3) \\ \Sigma(x^3) & \Sigma(x^2) \end{pmatrix}}^{\mathbf{A}} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} \Sigma(x^2y) \\ \Sigma(xy) \end{pmatrix} = \mathbf{u}$.

- (ii) Recall that if $\mathbf{M} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then $\mathbf{M}^{-1} = \frac{1}{\det(\mathbf{M})} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$. Thus

$$\begin{pmatrix} \Sigma(x^4) & \Sigma(x^3) \\ \Sigma(x^3) & \Sigma(x^2) \end{pmatrix}^{-1} = \frac{1}{\Sigma(x^4)\Sigma(x^2) - (\Sigma(x^3))^2} \begin{pmatrix} \Sigma(x^2) & -\Sigma(x^3) \\ -\Sigma(x^3) & \Sigma(x^4) \end{pmatrix}.$$

Considering $\mathbf{A}^{-1}\mathbf{A} \begin{pmatrix} a \\ b \end{pmatrix} = \mathbf{A}^{-1}\mathbf{u}$,

$$\begin{aligned} \begin{pmatrix} a \\ b \end{pmatrix} &= \frac{1}{\Sigma(x^4)\Sigma(x^2) - (\Sigma(x^3))^2} \begin{pmatrix} \Sigma(x^2) & -\Sigma(x^3) \\ -\Sigma(x^3) & \Sigma(x^4) \end{pmatrix} \begin{pmatrix} \Sigma(x^2y) \\ \Sigma(xy) \end{pmatrix} \\ &= \frac{1}{\Sigma(x^4)\Sigma(x^2) - (\Sigma(x^3))^2} \begin{pmatrix} \Sigma(x^2)\Sigma(x^2y) - \Sigma(x^3)\Sigma(xy) \\ -\Sigma(x^3)\Sigma(x^2y) + \Sigma(x^4)\Sigma(xy) \end{pmatrix}. \end{aligned}$$

Hence

$$\begin{aligned} a &= \frac{\Sigma(x^2)\Sigma(x^2y) - \Sigma(x^3)\Sigma(xy)}{\Sigma(x^4)\Sigma(x^2) - (\Sigma(x^3))^2} \\ b &= \frac{-\Sigma(x^3)\Sigma(x^2y) + \Sigma(x^4)\Sigma(xy)}{\Sigma(x^4)\Sigma(x^2) - (\Sigma(x^3))^2} \end{aligned}$$

- (d) Q is a sum of squares, so it is bounded below. Hence the values of a and b in (c)(i), which give a stationary value of Q , must correspond to a minimum value of Q .
- (e) (We are asked to find *approximate* values of a and b .) Note that for all the points, $x \approx y$. Hence $\Sigma(x^2y) \approx \Sigma(x^3)$ and $\Sigma(xy) \approx \Sigma(x^2)$. Using the result in (c)(ii), $a \approx 0$ and $b \approx 1$.

- 10 (a) (i)** $z = \exp(\frac{2\pi ki}{15})$ for $k = 0, \dots, 14$.
- (ii)** $z^{15} - 1 = (z^5)^3 - 1 = (z^5 - 1)(z^{10} + z^5 + 1)$. Let $z = \cos(\frac{2\pi}{15}) + i \sin(\frac{2\pi}{15}) = \exp(\frac{2\pi i}{15})$. Clearly $\exp(\frac{2\pi i}{15})$ is not a solution to $z^5 - 1 = 0$ so it must be that $z^{10} + z^5 + 1 = 0$.
- (iii)** $z^n + z^{-n} = \cos(n\theta) + i \sin(n\theta) + \cos(n\theta) - i \sin(n\theta) = 2 \cos(n\theta)$.
- (b)** Let $z = \cos(\frac{2\pi}{15}) + i \sin(\frac{2\pi}{15})$. Then $z^{10} + z^5 + 1 = 0$ so $z^5 + z^{-5} + 1 = 0$. See that $z^n + z^{-n} = 2 \cos(\frac{2n\pi}{15})$ so $2 \cos(5 \times \frac{2\pi}{15}) + 1 = 0$.
- By De Moivre's theorem notice that

$$\begin{aligned} \cos(5\theta) &= \Re[(\cos(\theta) + i \sin(\theta))^5] = \cos^5(\theta) - 10 \cos^3(\theta) \sin^2(\theta) + 5 \cos(\theta) \sin^4(\theta) \\ &= \cos^5(\theta) - 10 \cos^3(\theta)(1 - \cos^2(\theta)) + 5 \cos(\theta)(1 - \cos^2(\theta))^2 \\ &= 16 \cos^5(\theta) - 20 \cos^3(\theta) + 5 \cos(\theta). \end{aligned}$$

Hence $32 \cos^5(\frac{2\pi}{15}) - 40 \cos^3(\frac{2\pi}{15}) + 10 \cos(\frac{2\pi}{15}) + 1 = 0$. Set $x = 2 \cos(\frac{2\pi}{15})$ so $x^5 - 5x^3 + 5x + 1 = 0$. But then notice that $x^5 - 5x^3 + 5x + 1 = (x + 1)(x^4 - x^3 - 4x^2 + 4x + 1)$. Clearly $2 \cos(\frac{2\pi}{15}) + 1 \neq 0$ so it must be that $x^4 - x^3 - 4x^2 + 4x + 1 = 0$.

- (c)** We bound the value of $\cos(\frac{2\pi}{15})$. Recall that $\cos : (0, \pi) \rightarrow (-1, 1)$ is strictly decreasing, so $\frac{2}{15} = \frac{4}{30} < \frac{5}{30} = \frac{1}{6} \implies \cos(\frac{2\pi}{15}) > \cos(\frac{\pi}{6}) = \frac{\sqrt{3}}{2}$. We now have a reference point to compare the roots against.

Set $x = 2 \cos(\frac{2\pi}{15})$. We first compare $x_1 = \frac{1}{4}(1 - \sqrt{5} + \sqrt{6(5 + \sqrt{5})})$. Check that $\sqrt{5} > 1$ so

$$\frac{1}{4} \left(1 - \sqrt{5} + \sqrt{6(5 + \sqrt{5})} \right) \leq \frac{1}{4} \sqrt{6(5 + \sqrt{5})} \leq \frac{1}{4} \sqrt{6(5 + 3)} = \frac{\sqrt{48}}{2} = \sqrt{3} < 2 \cos\left(\frac{2\pi}{15}\right)$$

noting that $5 \leq 9 \implies \sqrt{5} \leq 3$. Hence $x \neq x_1$, and $x = x_2 = \frac{1}{4}(1 + \sqrt{5} + \sqrt{6(5 - \sqrt{5})})$.